

# Overview GENCNV MACHINE PROTECTION AND COLLISION DETECTION

## **Properties**

- Detection of dynamic collisions
- 3 independent acceleration sensor inputs with a frequency range of 10 Hz - 8 kHz and a sampling rate of 16 kHz with a resolution of 16 bits
- Physical I/O interface (3 inputs 4 outputs)
- 3 different operation modes
- 3 different static limits per mode
- Fast alarm output (< 1 ms)
- Recording of shutdown events
- Log file with signal values

If GEM**CMV** is connected to the GENIOR MODULAR system, the following additional signals are available for tool and process monitoring:

• 3 x acceleration (g)



#### Application example

GEMCMV is the ideal solution for detecting dynamic collisions. The following application example shows a GEMCMV acceleration measuring transducer with a VA-3D MEMS sensor and the GEMCMV Visu software (here via a control panel).



### GEMCMV in stand-alone mode

#### Additional features in stand-alone mode in combination with GEMCMV Visu

- Alarm event data recording
- Signal values stored in a .CSV log file
- Physical I/O interfaces (3 inputs, 4 outputs)

#### Available signals

3 x acceleration (m/s<sup>2</sup> or g)



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#### View from the left side

108,97

113,68

8

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Front view

| GENERAL DATA          |  |
|-----------------------|--|
| ARTICLE NUMBER        | 0830Z910102                              |
| STANDARD IP ADDRESS   | 192.168.214.100                          |
| DIMENSIONS            | see drawing                              |
| WEIGHT                | 0.196 kg                                 |
| MATERIAL              | Polyamide PA 6.6                         |
| STORAGE TEMPERATURE   | -20 °C+60 °C                             |
| OPERATING TEMPERATURE | +5 °C+50 °C                              |
| UL-CLASSIFICATION     | VO (UL94)                                |
| DEGREE OF PROTECTION  | IP30                                     |
| ATMOSPH.              | Storage < 95 %                           |
| REL. HUMIDITY         | Operation < 85 % + 85 % $\leq$ RH < 95 % |
| INSTALLATION          | DIN EN 60715 standard mounting rail      |
| CONTACTING            | Spring terminal, in-rail bus connector   |

| MEAS     | URING  |  |
|----------|--------|--|
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| MEASURING INPUTS | 3 x IEPE<br>suitable sensors (order separately):<br>all acceleration sensors with IEPE-interface<br>1 x RS485<br>(for VA-3D MG sensor) |
|------------------|--|
| ACCURACY         | < 0.5 %  |
| FREQUENCY RANGE  | 10 Hz 8 kHz  |
| SAMPLING RATE    | 16 kHz   |
| RESOLUTION       | 16 bit   |

#### SOFTWARE REQUIREMENTS VISUALIZATION

| OPERATING | SYSTEM  |
|-----------|---------|
| UPENAIING | STOTEIV |

| • | Microsoft Windows® as of                      |
|---|---|
| • | WIN XP SP3<br>Siemens 840D as of V 04.05. (P0 |



Perspective view

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| MINIMUM RAM                    | 512 MB        |
|--------------------------------|---------------|
| MIN. CLOCK FREQUENCY           | 600 MHz       |
| MOUSE/TOUCHSCREEN<br>OPERATION | recommended   |
| ETHERNET                       | 10/100 MBit/s |

| CONNECTIONS   |  |  |
|---|--|--|
| CONNECTION X1   | 24 V DC $\pm$ 20 %, max. 5 % ripple (or via in-rail bus connector X6)  |  |
| NOM. CURRENT CONSUMPTION  | max. 250 mA  |  |
| CONNECTION X2   | 3 x IEPE   |  |
| CONNECTION X3   |  |  |
| IN-/OUTPUT SIGNALS  | 3 input signals, 4 output signals                                      |  |
| INPUTS<br>1-SIGNAL SOURCE<br>0-SIGNAL SOURCE<br>1-SIGNAL SINK<br>0-SIGNAL SINK  | 8 V 36 V / 5 mA<br>0 V 7 V / 5 mA<br>0 V 19 V / 5 mA<br>20 V 36 V /5mA |  |
| OUTPUTS<br>1-SIGNAL SOURCE<br>0-SIGNAL SOURCE<br>1-SIGNAL SINK<br>0-SIGNAL SINK | 24 V typical, max. 100 mA<br>open<br>0 V 1 V<br>open                   |  |
| CONNECTION X6   | CAN bus  |  |
|   | 24 V DC  |  |
| CONFORMITY  | CE, UKCA   |  |

#### **OPERATION WITH GENIOR MODULAR**

Interface CAN bus CU/TCU) For a full list of address locations, please consult the Marposs official website



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